Online Change Detection via Random Fourier Features

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Collaborator



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(LSE department of Statistics)

LSE Research Showcase

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1 Introduction & problem statement

2 Kernel two sample tests

Online change detection

Theoretical results



▶ Setup: the sequence $X_1, X_2, ...$ is observed online. The X's are defined on \mathbb{R}^d , and $\exists \eta \in \mathbb{N}$ (possibly infinite) and two measures $\mathbb{P}, \mathbb{Q} \in M_1^+(\mathbb{R}^d)$ for which

$$X_t \stackrel{\text{i.i.d.}}{\sim} \begin{cases} \mathbb{P} & \text{ for } t = 1, \dots, \eta \\ \mathbb{Q} & \text{ for } t = \eta + 1, \eta + 2, \dots \end{cases}$$

Goal: stop the process with minimal delay as soon as η is reached, but not before.

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Goal: stop the process with minimal delay as soon as η is reached, but not before.

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- **Goal:** construct an extended stopping time *N* which is guaranteed to be "close" to η and which satisfies either of
 - 1. Average run length: $\mathbb{E}_{\infty}[N] \ge \gamma$ for some $\gamma > 1$,
 - 2. Uniform false alarm rate: $\mathbb{P}_{\infty} \left(N \leqslant \infty
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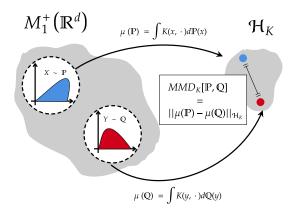
Definition (RKHSs)

A Hilbert space \mathcal{H}_K with inner product $\langle \cdot, \cdot \rangle_{\mathcal{H}_K}$ and norm $\|\cdot\|_{\mathcal{H}_K}$ consisting of functions $f : \mathbb{R}^d \mapsto \mathbb{R}$ is called an RKHS if there exists a kernel $K : \mathbb{R}^d \times \mathbb{R}^d \mapsto \mathbb{R}$ for which

- $K(x, \cdot) \in \mathcal{H}_{K}$ for all $x \in \mathbb{R}^{d}$
- $f(x) = \langle f, K(x, \cdot) \rangle_{\mathcal{H}_{K}}$ for all $x \in \mathbb{R}^{d}$ and all $f \in \mathcal{H}_{K}$ (reproducing property).
- ▶ Kernel methods: represent data as elements of H_K using K(x, ·), do learning in H_K. Due to the reproducing everything can be expressed in terms of K(x, y) ⇒ actually computable.

Maximum Mean Discrepancy

The Maximum Mean Discrepancy (Gretton u. a., 2012, MMD) measures discrepancies between distributions by considering their distance in RKHS norm.



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• If $MMD_{\mathcal{K}}[\mathbb{P},\mathbb{Q}] = 0 \Leftrightarrow \mathbb{P} = \mathbb{Q}$ then $\mathcal{H}_{\mathcal{K}}$ is called characteristic. Sriperumbudur u.a. (2010) have shown that $\mathcal{H}_{\mathcal{K}}$ is characteristic if

(C1) $\sup_x \sqrt{K(x,x)} \leq C$ for some C > 0 (bounded) (C2) $K(x,y) = \psi(x-y)$ for some positive definite ψ (translation

C3) supp $(\Lambda) = \mathbb{R}^d$ with $\psi(x) = \int e^{-i\omega'x} d\Lambda(\omega)$ (spectrum support)

Some examples of characteristic kernels include...

Kernel	$\psi(x)$	$\Lambda(\omega)$	$supp(\Lambda)$
Gaussian	$e^{-x^2/(2\sigma^2)}$	$\sigma e^{-\sigma^2 \omega^2/2}$	
Laplace	$e^{-\sigma x }$		
B_{2n+1} —spline	$*_{1}^{(2n+1)}1_{\left[-\frac{1}{2},\frac{1}{2} ight]}(x)$	$\frac{4^{n+1}}{\sqrt{2\pi}} \frac{\sin^{2n+2}(\omega/2)}{\omega^{2n+2}}$	

... to extend to \mathbb{R}^d take products.

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Maximum Mean Discrepancy (continued)

Given independent samples {X₁,..., X_n} ~ ℙ and {Y₁,..., Y_m} ~ ℚ a natural estimator of the (squared) MMD is given by

$$\mathsf{MMD}_{K}^{2}[X_{1:n}, Y_{1:m}] = \left\| \mu(\hat{\mathbb{P}}_{1:n}) - \mu(\hat{\mathbb{Q}}_{1:m}) \right\|_{\mathcal{H}}^{2}$$

• Computing the above requires $O(n^2 + m^2)$ basic operations making its use impractical for online problems.

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$$\mathsf{MMD}_{K}^{2}[X_{1:n}, Y_{1:m}] = \frac{1}{n^{2}} \sum_{i=1}^{n} \sum_{j=1}^{n} K(X_{i}, X_{j}) + \frac{1}{m^{2}} \sum_{i=1}^{m} \sum_{j=1}^{m} K(Y_{i}, Y_{j}) - \frac{2}{nm} \sum_{i=1}^{n} \sum_{j=1}^{m} K(X_{i}, Y_{j}).$$

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Let K satisfy C1-C3. By Bochner's theorem

$$K\left(x,y\right)=\int_{\mathbb{R}^{d}}e^{i\omega'\left(x-y\right)}\mathrm{d}\Lambda\left(\omega\right).$$

Rahimi und Recht (2007) note that as both Λ, K are real the integrand must be real and by Euler's identity can be replaced with cos (ω' (x - y)). Thus

$$K(x,y) = \int_{\mathbb{R}^d} \cos\left(\omega'(x-y)\right) d\Lambda(\omega) = \mathbb{E}_{\omega \sim \Lambda}\left[\cos\left(\omega'(x-y)\right)\right].$$

▶ Then for $r \in \mathbb{N}$ and $\omega_1, \ldots, \omega_r \stackrel{i.i.d}{\sim} \Lambda$ an unbiased estimator for K(x, y) is

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For r∈ N and ω₁,..., ω_r ^{i.i.d} ∧ given independent samples {X₁,..., X_n} ~ P and {Y₁,..., Y_m} ~ Q a simple unbiased estimator of MMD²_K [X_{1:n}, Y_{1:m}] is

$$\mathsf{MMD}_{\hat{K}}^{2}\left[X_{1:n}, Y_{1:m}\right] = \left\|\frac{1}{n}\sum_{i=1}^{n}\frac{1}{r}\sum_{k=1}^{r}z_{\omega_{k}}\left(X_{i}\right) - \frac{1}{m}\sum_{j=1}^{m}\frac{1}{r}\sum_{k=1}^{r}z_{\omega_{k}}\left(Y_{j}\right)\right\|_{2}^{2}.$$

where $z_{\omega}(x) = (\cos(\omega' x), \sin(\omega' x))'$.

Importantly, this quantity can be computed in O (*rn* + *rm*) basic operations, and updated in O(*r*) time, making it ideal for online problems.

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Kernel two sample tests



4 Theoretical results



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• Recall, the aim is to test H_0 in an online manner against

$$H_{1,n}: \exists \eta < n \text{ s.t } X_t \sim \begin{cases} \mathbb{P} & \text{ if } 1 \leqslant t \leqslant \eta \\ \mathbb{Q} & \text{ if } \eta < t \leqslant n \end{cases}, \text{ and } \mathbb{P}, \mathbb{Q} \in M_1^+(\mathbb{R}).$$

This can be achieved with the statistic

$$\max_{\tau=1...n-1} \sqrt{\frac{\tau(n-\tau)}{n}} \mathsf{MMD}_{\widehat{K}} \left[X_{1:\tau}, X_{(\tau+1):n} \right].$$

We use a dyadic approximation scheme due to Lai (1995)

$$N = \inf\left\{n \ge 2 \mid \bigvee_{j=0}^{\lfloor \log_2(n) \rfloor - 1} \sqrt{\frac{2^j(n-2^j)}{n}} \mathsf{MMD}_{\hat{K}}\left[X_{1:(n-2^j)}, X_{(n-2^j+1):n}\right] > \lambda_n\right\}$$

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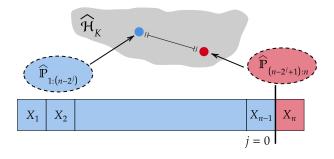
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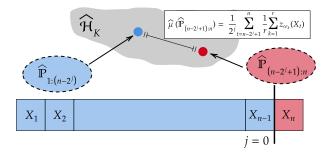
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Having observed data {X₁,..., X_n}, we consider log₂(n) possible sample splits. For every such split we approximate the MMD between empirical measures of the two samples using RFFs, and stop the process at the first n for which at least one such statistic is larger than a given threshold.



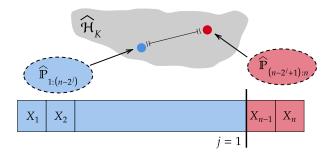
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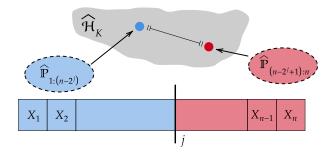
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Explicit Algorithm

Algorithm 1: RFF MMD Change Detector **Data:** $X_1, X_2, \ldots, \alpha \in (0, 1)$ Result: Changepoint location and detection time 1 $W \leftarrow \text{empty list}$: **2** for $X_t \in X_1, X_2, \ldots$; /* Main loop */ 3 do $W.c \leftarrow 1$; 4 5 $W.z \leftarrow z_k(X_t)$; $\mathcal{W} \leftarrow \mathcal{W}.append(W)$; 6 for $i \in 1, ..., |\mathcal{W}| - 1$: 7 /* Detect changes */ 8 do $n \leftarrow \sum_{i=i+1}^{|\mathcal{W}|} \mathcal{W}_{i.c};$ 9 $m \leftarrow \sum_{i=1}^{i} W_{i.c}$; 10 $\text{MMD}_{\hat{k}} \leftarrow \left\| \frac{1}{n} \sum_{j=i+1}^{|W|} W_{j,z} - \frac{1}{m} \sum_{j=1}^{i} W_{j,z} \right\|_{0};$ 11 $\alpha' \leftarrow \alpha/(|\mathcal{W}| - 1)$: 12 if $\sqrt{\frac{nm}{n+m}} MMD_{\hat{K}} \ge \lambda$ then 13 **print** Change detected at element X_t ; most likely at i; 14 Drop tail of W : 15 end 16 end 17 while $|\mathcal{W}| \ge 2$; /* Maintain exponential structure */ 18 19 do 20 $W_1 \leftarrow \text{pop } \mathcal{W}$; $W_2 \leftarrow \text{pop } \mathcal{W}$; 21 if $W_1.c = W_2.c$ then 22 $W.c \leftarrow W_{1,c} + W_{2,c}$: 23 $W.z \leftarrow W_{1}.z + W_{2}.z$; 24 25 $\mathcal{W} \leftarrow \mathcal{W}.append(W)$; else 26 break : 27 end 28 29 end

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Time Complexity: $\mathcal{O}(r \log(n))$ per iteration

- Setup: The computation of $z_{\omega_k}(X)$ requires computing 2r trigonometric functions of *d*-dimensional inner products and thus is in $\mathcal{O}(rd)$.
- Change detection: The memoization of all sums allows to implement the change detection in a single sweep over W; at each step, the attributes of one W ∈ W are subtracted from one sum and added to another sum. This gives a total complexity of O(r log(n))
- Maintenance: In the worst case, O(log(n)) merge operations need to be performed. Each merge requires O(r) operations, which yields a total cost of O(r log(n)).

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Kernel two sample tests

3 Online change detection

Theoretical results

Numerical studies

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Theorem (average run length)

Let N be the extended stopping time defined previously. For any $\gamma>$ 1, if the sequence of thresholds satisfies

$$\lambda_{\textit{n}} \geqslant \sqrt{2} + \sqrt{2 \log \left(4 \gamma \log_2 \left(2 \gamma \right)\right)} \quad \textit{n} \in \mathbb{N}$$

it holds that $\mathbb{E}_{\infty}[N] \ge \gamma$.

Note that the above result does not depend on the number of random Fourier features used to approximate the MMD.

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Theorem (uniform false alarm rate)

Let N be the extended stopping time defined previously. For any $\alpha \in (0,1)$, if the sequence of thresholds satisfies

$$\lambda_n \ge \sqrt{2} + \sqrt{2\left(\log(n/\alpha) + 2\log\left(\log_2(n)\right) + \log\left(\log_2(2n)\right)\right)} \quad n \in \mathbb{N}$$

then it holds that $\mathbb{P}_{\infty}(N < \infty) \leq \alpha$.

Note that the above result does not depend on the number of random Fourier features used to approximate the MMD.

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Theorem (high probability detection delay)

Let λ_n be as defined in the previous theorem. If supp $(\mathbb{P}) \cup$ supp $(\mathbb{Q}) \subseteq \mathcal{X}$ for some compact set $\mathcal{X} \subset \mathbb{R}^d$,

$$\eta \geq rac{C_1 \log \left(2\eta/\alpha\right)}{MMD_K^2 \left[\mathbb{P}, \mathbb{Q}\right]},$$

and moreover the number of random features is chosen so that

$$\sqrt{r} \ge rac{C_2 + C_3 \sqrt{2 \log (2/\alpha)}}{MMD_{\mathcal{K}}^2 \left[\mathbb{P}, \mathbb{Q}\right]}$$

then with probability at least $1-\alpha$ it holds that

$$\left(\mathsf{N}-\eta
ight)^{+}\leqslant1eerac{\mathsf{C}_{\mathsf{4}}\log\left(2\eta/lpha
ight)}{\mathsf{MMD}_{\mathsf{K}}^{2}\left[\mathbb{P},\mathbb{Q}
ight]}$$

where C_1, C_2, C_3 , and C_4 are absolute constants.

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Kernel two sample tests

3 Online change detection

4) Theoretical results

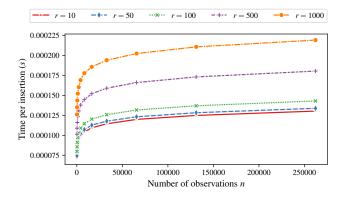


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Runtime Experiments

 Average runtime (10 repetitions) under the null of no change of the RFF-MMD algorithm using r ∈ {10, 50, ..., 1000} random Fourier features in dimension d = 1.



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We compare with three state of the are methods for online change detection...

Name	Time complexity	Approach	Training data
RFF-MMD	$r \log(n)$	$RFF + dyadic \ scheme$	No
ScanB	NW^2	sliding window	Yes
OKCUSUM	NW^2	max over multiple windows	Yes
NewMA	rd	RFF + exponential moving average	No

... for ScanB and OKCUSUM: N denotes the number of windows and W denotes the (max) window size.

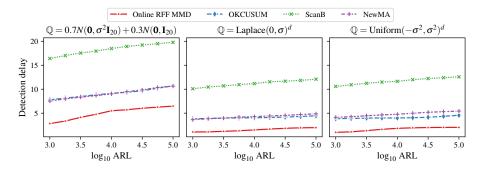
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Average Detection Delay Experiments

Average detection delay (1000 repetitions) from 64 samples of

 \[P = \mathcal{N}(\mathbf{0}_{20}, \mathcal{I}_{20})\]
 to the distribution indicated on top. r = 1000 random

 Fourier features are used to approximate the MMD, and thresholds for each
 method are calibated vai Monte Carlo.



Thank you!

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