

Rank-based models with listings and delistings

Theory and calibration

David Itkin London School of Economics and Political Science (LSE)

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Joint work in progress with Martin Larsson, Licheng Zhang (CMU)

Local Model



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Long-term modelling of financial markets



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- Many market participants are interested in long-time horizons
 - Pension funds, Trust funds, Endowments, etc.
- We will focus on equity markets (stocks).
- Modelling any noisy system over a long period of time is challenging. \rightarrow but may be rewarding!

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Long-term modelling of financial markets

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Questions:

- What features of equity markets persist over long-time horizons
- Can we develop models capturing such features and procedures for statistical calibration?

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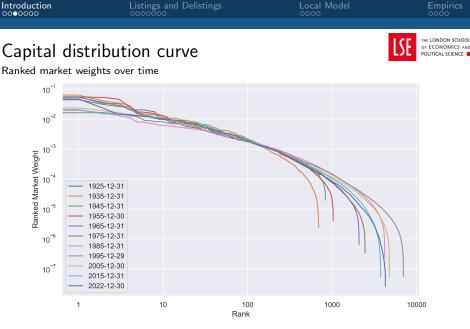
Capital distribution curve

- Let S_1, \ldots, S_N denote the market capitalization processes of N companies.
- Set

$$\mu_i(t) = \frac{S_i(t)}{S_1(t) + \cdots + S_N(t)} \qquad i = 1, \dots, N$$

to be the market weights.

• The ranked market weights $\mu_{(1)} \ge \mu_{(2)} \ge \cdots \ge \mu_{(N)}$ are remarkably stable over time.



Data Source: CRSP

First-order ranked based models



- Curve stability was first observed by Robert Fernholz who developed Stochastic Portfolio Theory (SPT) in 2002
 - SPT further developed together with Ioannis Karatzas, his students including Kardaras, Ruf and many others.

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- Fernholz proposed rank-based models, which are reduced-form models that can capture the empirical stability of the curve
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- Letting $X_i = \log S_i$ the model postulates dynamics

 $dX_i(t) = \gamma_{r_i(t)}dt + \sigma_{r_i(t)}dW_i(t)$

where $\gamma_i \in \mathbb{R}$, $\sigma_i > 0$, $r_i(t)$ is the rank asset *i* occupies at time *t* and *W* is an *N*-dimensional Brownian Motion.



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• Under the stability condition

$$\bar{\gamma} := \frac{1}{N} \sum_{k=1}^{N} \gamma_k > \frac{1}{n} \sum_{k=1}^{n} \gamma_k, \quad n = 1, \dots, N-1,$$

the market weights are ergodic representing stability of the curve.

• When $\gamma_N \gg \gamma_i$ for every other *i* we say the model is Atlas-like.



- Ranked log-caps: $X_{(1)} \ge X_{(2)} \ge \cdots \ge X_{(N)}$.
- Ranked dynamics:

$$dX_{(k)}(t) = \gamma_k dt + \sigma_k d\widetilde{W}_k(t) + \frac{1}{2} d\Lambda_k(t) - \frac{1}{2} d\Lambda_{k-1}(t),$$

where Λ_k is the local time at zero of $X_{(k)} - X_{(k+1)}$ and $\Lambda_0 = \Lambda_N = 0$.

 This term Λ_k activates when two particles collide X_(k) = X_(k+1) and ensures the ordering X_(k) ≥ X_(k+1) persists



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- Volatility calibration: $\sigma_k^2 = \frac{d[X_{(k)}](t)}{dt}$,

 $\rightarrow\,$ standard estimation using quadratic variation.

Parameter calibration



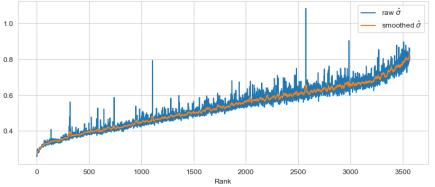
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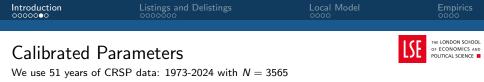
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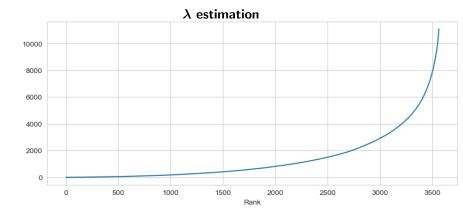
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- Volatility calibration: $\sigma_k^2 = \frac{d[X_{(k)}](t)}{dt}$,
 - \rightarrow standard estimation using guadratic variation.
- Drift calibration: $\gamma_k \bar{\gamma} = \frac{1}{2} \lim_{T \to \infty} (\frac{1}{T} \Lambda_{k-1}(T) \frac{1}{T} \Lambda_k(T)).$
 - \rightarrow Requires estimating collision rates $\lambda_k = \frac{1}{2} \lim_{T \to \infty} \frac{1}{T} \Lambda_k(T)$.
 - → Efficient method using a so-called "Master formula" for portfolio generation available and developed in Fernholz (2002)









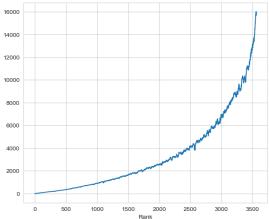
Local Model



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Calibrated Parameters

We use 51 years of CRSP data: 1973-2024 with N = 3565



volatility normalized λ/σ^2

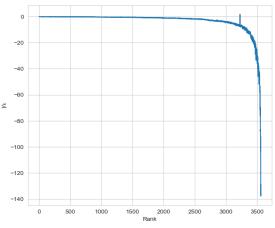
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γ estimation

Not plotted: $\gamma_d \approx 11000$

Introduction 000000●	Listings and Delistings	Local Model	Empirics 0000
Puzzles			THE LONDON SCHOOL OF ECONOMICS AND POLITICAL SCIENCE

• Why are λ 's increasing more and more rapidly?

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- Why are λ 's increasing more and more rapidly?
 - λ_k represents volatility-weighted rate of collisions,
 - the estimates imply rate is monotonically increasing across all ranks.
 - Persists even when accounting for volatility.
 - But aren't there fewer stocks at the tail end?

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 - Directly linked to one-sided collision at final rank.
 - Artefact of the model due to fixed number of stocks.
 - Is there a simple ad-hoc way to modify the estimates?
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Issues seem to be linked with the smallest stock/fixed universe.

- We try to address this by allowing for listings and delistings.
 - How prevalent are they?
- Campbell & Wong (2024) identified these as important drivers for capital distribution curve stability.

Listings and Delistings



- We model a variable equity universe with a focus on developing estimators for empirical calibration,
 - Some recent literature on equity models with variable assets: Sarantsev & Karatzas (2016), Bayraktar, Kim & Tilva (2024)
 - Open markets are another related approach: Fernholz (2018), Karatzas & Kim (2020), Itkin & Larsson (2024).

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 $dX_i(t) = \gamma_{r_i(t)}dt + \sigma_{r_i(t)}dW_i(t), \quad \beta_i \leq t \leq \delta_i,$

where $r_i(t)$ is the rank of asset *i* at time *t* among the listed assets.





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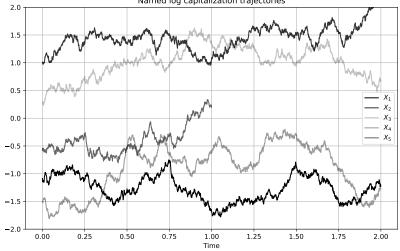
- We set $I(t) = \{i : t \in [\beta_i, \delta_i]\}$ and N(t) = |I(t)|.
- We assume nondegeneracy: $N(t) \ge 1$ and finite activity: $\sum_{t \le T} \Delta N(t) < \infty$ for every T > 0.

- Despite X_i being continuous on its lifetime X₍₎ experiences jumps at listing and delisting times.
- Moreover, the market capitalization $\Sigma(t) = \sum_{i \in I(t)} S_i(t)$, the market weights

$$\mu_i(t) = \frac{S_i(t)}{\Sigma(t)} \mathbb{1}_{\{i \in I(t)\}},$$

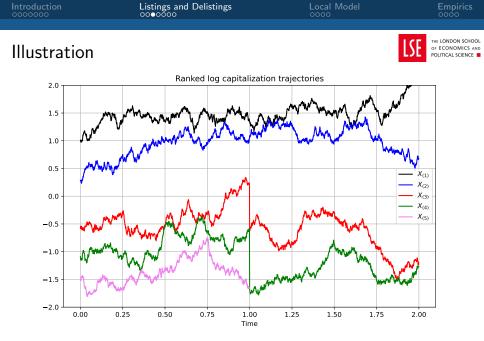
and the ranked market weights $\mu_{()}(t)$ experience jumps as well.



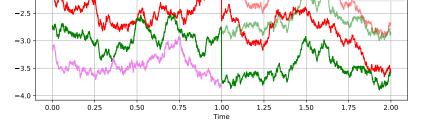


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 $(\log \mu^c)_0$

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- Jumps have a larger effect on the smaller ranks.
- Care is needed dealing with portfolios and the collision estimator.
- Indeed, the wealth $V^{\mathcal{M}}$ of an investor trading the market portfolio now satisfies

 $\log V^{\mathcal{M}}(t) = \log \Sigma^{\boldsymbol{c}}(t),$

whereas classically $\log V^{\mathcal{M}}(t) = \log \Sigma(t)$.

Collision estimation with listings/delistings



- We developed a new "Master formula" for portfolio generation in this setting with listings and delistings.
- As in the classical setting the collision estimator can be derived by looking at the large-cap portfolio investing in the top k assets.
- In the fixed investment universe

$$d\Lambda_k(t) = \frac{\mu_{(1)}(t) + \cdots + \mu_{(k)}(t)}{\mu_{(k)}(t)} d \log\left(\frac{V^{\mathcal{M}_k}}{V^{\mathcal{M}}} \times \frac{1}{\mu_{(1)} + \cdots + \mu_{(k)}}\right)(t)$$

• With listings/delistings (on the set $\{|I(t)| \ge k\}$):

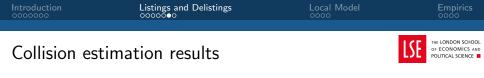
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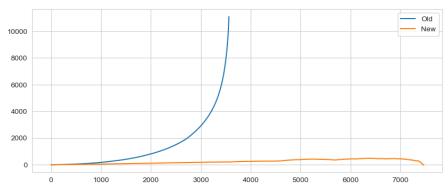
where $\log \tilde{\mu}(t) = \log \mu^{c}(t)$.



Rank

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A comparison



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where $\log \tilde{\mu}(t) = \log \mu^{c}(t)$.

The original estimator registers rank change caused by a listing/delisting as a collision.

- Although the original estimator is consistent in the fixed asset model, when applied to real data, it produces bias.
- The bias propogates effecting the smallest stocks the most since a listing/delisting at rank k causes a jump for each μ_(ℓ), ℓ > k.

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- Particle Density
 - What is a driver of collisions?
 - Naively, we expect
 - More collisions, if highly volatile,
 - Fewer collisions if neighbours are positively correlated,
 - More collisions if particles tightly packed.



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• We define average particle density at rank k as

$$\phi_k = \lim_{T\to\infty} \frac{1}{T} \int_0^T \frac{2n-1}{X_{(k-n)}(t) - X_{(k+n)}(t)} dt.$$

for a hyperparameter n.



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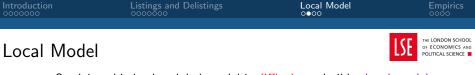
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What is the relationship between σ_k, ρ_k, ϕ_k and how is this related to the collision rates λ_k ?



- Studying this in the global model is difficult, so build a local model.
- Idea: For a fixed rank k create a synthetic large particle model where a typical particle behaves like our rank k one.



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- We choose the following model

$$dX_i^N(t) = -\frac{\sigma^2}{2}X_i^N(t)dt + \sigma dW_i(t), \quad i = -N, \ldots, 0, \ldots, N,$$

with $d[W_i, W_j](t) = \rho dt$ for all $i \neq j$.

• This is an Ornstein–Uhlenbeck process with stationary measure $N(0, \Sigma_N)$ where $\Sigma_N = (1 - \rho)I_N + \rho I_{N \times N}$.



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- To study rank k we would take $\sigma = \sigma_k$, $\rho = \rho_k$, start the process at stationarity and study the median particle $X_{(0)}$ as the typical one.
 - The analysis leads to the same conclusion for any fixed quantile.



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 - The analysis leads to the same conclusion for any fixed quantile.
- We are interested in understanding the relationship between σ, ρ, λ and ϕ as $N \to \infty$.

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 Empirics

 Some order statistics results

 Introduction
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- We can write $X_i^N = \sqrt{\rho}Y + \sqrt{1-\rho}Z_i^N$ where Y and $(Z_i^N; i = -N, ..., N)$ are IID N(0,1) random variables.
- Hence the gaps satisfy $X_i^N X_j^N = \sqrt{1 \rho} (Z_i^N Z_j^N)$ so it is enough to study the IID case.

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Listings and Delistings

• Hence the gaps satisfy $X_i^N - X_j^N = \sqrt{1 - \rho} (Z_i^N - Z_j^N)$ so it is enough to study the IID case.

Proposition (I., Larsson, Zhang (2025+))

- Then density f^N on $[0, \infty)$ of the random variable $N(Z_{(0)}^N Z_{(1)}^N)$ satisfies $\lim_{N\to\infty} f^N(0) = \sqrt{2/\pi}$.
- **2** The random variable $N(Z_{(-n)} Z_{(n)})$ converges in distribution as $N \to \infty$ to a $\Gamma(2n, \sqrt{2/\pi})$ random variable.
- The weak convergence in part two extends to the unbounded function h(x) = 1/x.



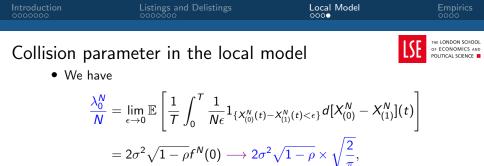




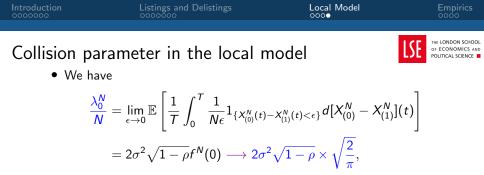


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Collision pa	rameter in the local m	nodel	THE LONDON SCHOOL OF ECONOMICS AND POLITICAL SCIENCE
 We have 	ve		

$$\begin{split} \frac{\lambda_0^N}{N} &= \lim_{\epsilon \to 0} \mathbb{E} \left[\frac{1}{T} \int_0^T \frac{1}{N\epsilon} \mathbb{1}_{\{X_{(0)}^N(t) - X_{(1)}^N(t) < \epsilon\}} d[X_{(0)}^N - X_{(1)}^N](t) \right] \\ &= 2\sigma^2 \sqrt{1 - \rho} f^N(0) \longrightarrow 2\sigma^2 \sqrt{1 - \rho} \times \sqrt{\frac{2}{\pi}}, \end{split}$$



$$\frac{\phi_0^N}{N} = \mathbb{E}\left[\frac{2n-1}{N(X_{(-n)}-X_{(n)})}\right] \longrightarrow (2n-1)\int_0^\infty \frac{\lambda^{2n}}{\Gamma(2n)} x^{2n-2} e^{-\sqrt{2/\pi x}} dx$$
$$= \sqrt{\frac{2}{\pi}} \times \frac{1}{\sqrt{1-\rho}}.$$



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- Hence, $\phi_0^N \approx \frac{\lambda_0^N}{2\sigma^2(1-\rho)}$.
- Let see how the listing and delisting model performs with real data.

Listings and Delisting

Local Model

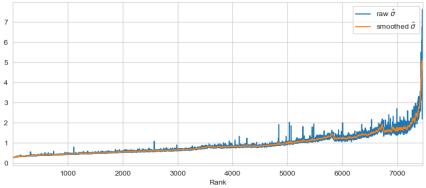
Empirics

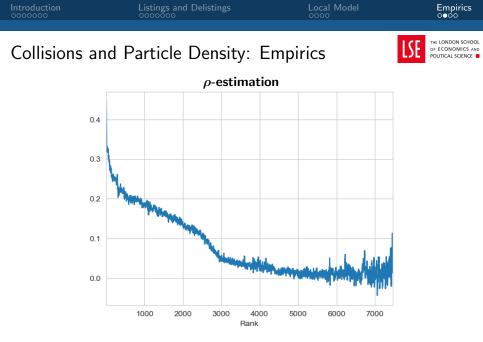
Collisions and Particle Density: Empirics



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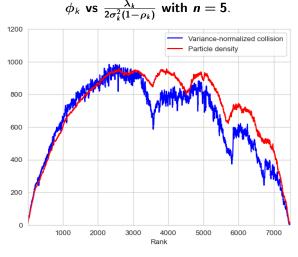
Listings and Delisting

Collisions and Particle Density: Empirics

Local Model

LSE

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A more granular look?



Summary of results

Conclusion and future work

- Introduced a rank-based model with listings and delistings,
- Derived a new master formula for portfolio generation
- Derived collision estimator accounting for listings/delistings, which corrects bias of previously used estimator when applied to real data,
- Studied local model and connected collisions to particle density.

To be done:

- Estimate listing and delisting rates,
- Pick a (Markovian) birth/death mechanism for global model,
- Conduct numerical and simulation experiments for global model.
- Theoretical analysis of global model?



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Thank you!

Master Formula for Functional Generation





• In this setting we say a portfolio π is functionally generated if

$$\log\left(\frac{V^{\pi}(T)}{V^{\mathcal{M}}(T)}\right) = \log\left(\frac{G(\tilde{\mu}(T))}{G(\tilde{\mu}(0))}\right) + \Gamma(T)$$

for some function $G: \bigcup_d \mathbb{R}^d \to \mathbb{R}$ and process of finite variation Γ .

• Here $\log \tilde{\mu}(t) = \log \mu^{c}(t) \longrightarrow$ differs from the standard setting.

Theorem (I., Larsson, Zhang 2025+)

For a C^2 function F, the portfolio $\pi_i(t) = \sum_k \eta_k(t-) \mathbb{1}_{\{r_i(t-)=k\}}$ which invests

$$\eta_k(t) = ilde{\mu}_{(k)}(t) \left(\partial_k \log F(ilde{\mu}_{()}(t)) + rac{1 - \sum_{\ell=1}^{N(t)} ilde{\mu}_{(\ell)}(t) \partial_\ell \log F(ilde{\mu}_{()}(t))}{\sum_{\ell=1}^{N(t)} ilde{\mu}_{(\ell)}(t)}
ight) 1_{\{k \leq |I(t)|\}}$$

in the asset at rank k is functionally generated by $G(x) = F(x_{()})$ with

$$d\Gamma(t) = -\frac{1}{2} \sum_{k,\ell=1}^{N(t)} \frac{\partial_{k\ell} F(\tilde{\mu}(t))}{F(\tilde{\mu}(t))} d[\tilde{\mu}_{(k)}, \tilde{\mu}_{(\ell)}](t) - \frac{1}{2} \sum_{k=1}^{N(t)} (\eta_k(t) - \eta_{k+1}(t)) d\Lambda_k(t).$$

Collision rates estimation



• Applying this with the function $F(x) = x_{(1)} + \cdots + x_{(k \wedge d)}$ for $x \in \mathbb{R}^d$ yields that the large-cap portfolio of size k,

$$\pi_{i}(t) = \frac{\tilde{\mu}_{i}(t)}{\tilde{\mu}_{(1)}(t) + \dots + \tilde{\mu}_{(k \wedge N(t))}(t)} \mathbb{1}_{\{r_{i}(t-) \leq k\}}$$
$$= \frac{\mu_{i}(t-)}{\mu_{(1)}(t-) + \dots + \mu_{(k \wedge N(t-))}(t-)} \mathbb{1}_{\{r_{i}(t-) \leq k\}}$$

has wealth process

$$\log\left(\frac{V^{\mathcal{M}_{k}}(T)}{V^{\mathcal{M}}(T)}\right) = \log\left(\frac{\tilde{\mu}_{(1)}(T) + \dots + \tilde{\mu}_{(k \wedge N(T))}(T)}{\tilde{\mu}_{(1)}(0) + \dots + \tilde{\mu}_{(k \wedge N(0))}(0)}\right) + \frac{\tilde{\mu}_{(k \wedge N(t))}(t)}{\tilde{\mu}_{(1)}(t) + \dots + \tilde{\mu}_{(k \wedge N(t))}(t)}d\Lambda_{k}(t),$$

with the convention that $d\Lambda_k(t) = 0$ on $\{|I(t)| < k\}$.

Discretized Estimators

• Old estimator for local time



$$\frac{1}{T}\sum_{i=0}^{M-1}\frac{S_{(1)}(t_i)+\dots+S_{(k)}(t_i)}{S_{(k)}(t_i)}\log\left(\frac{S_{(1)}(t_i+1)+\dots+S_{(k)}(t_i+1)}{S_{n_1(t_i)}(t_i+1)+\dots+S_{n_k(t_i)}(t_i+1)}\right),$$

where $n_k(t)$ is the name occupying the k'th rank at time t.

• New estimator for local time:

$$rac{1}{Tp(k)} \sum_{i=0}^{M-1} \mathbb{1}_{\{|I(t_i)| \geq k\}} rac{S_{(1)}(t_i) + \cdots + S_{(k)}(t_i)}{S_{(k)}(t_i)} \ imes \log \left(rac{S_{J^{t_i,t_i+1}_{(1)}}(t_i+1) + \cdots + S_{J^{t_i,t_i+1}_{(k)}}(t_i+1)}{S_{J^{t_i,t_i}_{(1)}}(t_i+1) + \cdots + S_{J^{t_i,t_i}_{(k)}}(t_i+1)}
ight),$$

where

- $p(k) = \frac{1}{M} \sum_{i=0}^{M-1} 1\{|I(t_i) > k|\},\$
- $J_{(\ell)}^{t,s}$ is the name of of ℓ 'th largest market cap based on time *s* values and out of only the names that are listed at time *t* and t + 1.