





LSE Cities Briefing Papers

## Hybrid Cities Briefing Paper 2: Public Space, Connected People and Autonomous Systems

by Philipp Rode and Sudeep Bhargava

22 July 2024

#### Acknowledgements

This LSE Cities Briefing Paper was prepared as part of the "Towards a Hybrid Cities Programme" pilot project, funded by the Ove Arup Foundation.

### 1 Introduction

As digital connectivity and autonomous systems become increasingly pervasive in the public spaces and streets of our cities, reassessing the relationships between people's interactions, their behaviours, moving artifacts and public urban environments will become an increasingly necessary part of future city development. Critically analysing these relationships will assist proactive responses to future sociability needs, safety concerns and urban inclusion demands associated with the public realm of cities. Since its conceptualisation, research on hybridurban space has been concerned with the shift from desktops to handheld devices and the mobile digital-physical interactions of pedestrians (de Souza e Silva, 2006). Utilising the Hybrid Cities Lab's approach<sup>1</sup> to urban hybridity, we have constructed an ecosystem of inquiry, depicted in Figure 1, around the nexus of public city space, virtually connected people and autonomous systems that we share space with. Various types of hybrid activities undertaken by people on a daily basis are tied to autonomous transport in urban mobility systems and augmented reality (AR) technologies that are becoming increasingly popular. This review will use three nexuses of inquiry, depicted in Figure 2, to analyse the interactions within the larger ecosystem.

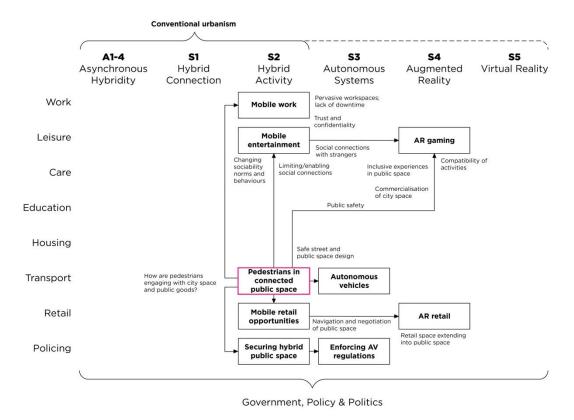


Figure 1. Public space, connected people and autonomous systems ecosystem.

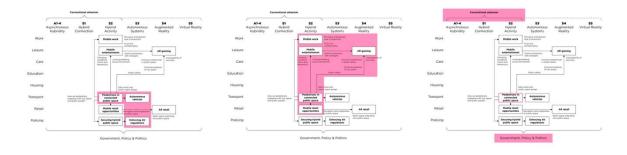


Figure 2. Three nexuses: (A) People and autonomous vehicle interaction; (B) People, devices and data; and (C) Public space and street design.

# 2 Nexus A: People and autonomous vehicle interaction

Autonomous vehicle (AV) services are estimated to be widely available to the urban public within a decade. Pilot projects in diverse cities including San Francisco, London, Singapore and Wuhan, have completed safety trials with driverless cars and robotaxis (ServCity, 2023, White, 2024). However, many cities worldwide remain far from even limited integration of autonomous vehicles into their transport ecosystems. Sharing road space with non-autonomous vehicles, motorists, cyclists and pedestrians presents many safety risks, prompting further research into pedestrian-AV interaction. This interaction is increasingly taking place via external human-machine interfaces, which enable simple and explicit communication between pedestrians and AVs (Zhanguzhinova et al., 2023) and lead to a greater acceptance of, and response to, AVs (Bellet et al., 2022). Wearable AR presents another way to reduce pedestrians' cognitive load when interacting with AVs on the road (Tran et al., 2022). Inside the vehicle, researchers have been studying the effective adoption of technologies such as AR head-up displays to improve road safety overall (Xia et al., 2023).

The perceived impacts of AVs on urban mobility systems have been tested using various methods, including modelling, surveys and critical analyses. AVs have the potential to significantly improve road safety, reduce emissions, optimise travel time and lower congestion levels (Severino et al., 2021). However, their successful implementation requires more attention. Kalatian and Farooq (2021) use immersive virtual reality to analyse factors which affect pedestrian behaviour in the presence of AVs. Guerreiro Augusto et al. (2024) show how automated mobility becomes intertwined with distributed AI and the platform economy in developing urban automated transport systems. Their 'architectural blueprint' provides an initial entry point into "building effective and efficient MaaS solutions for citizens" (Guerreiro Augusto et al., 2024, p.9). Gouni, Kehagia and Nalmpantis (2022) argue that carsharing services must be a central component of any proposed automated

urban mobility system to achieve the desired sustainability results and positively affect demand for public transport. From citizens' perspectives, survey data shows that respondents exhibit an overall positive acceptance of last-mile autonomous shuttle services, but with a limited willingness to pay for them (Camps-Aragó et al., 2022).

Trials on pedestrian detection by AVs revealed significant safety risks for pedestrians and human drivers. The researchers call for a re-evaluation of "performance standards for cars that embed probabilistic reasoning, since it is clear from [their] results that despite manufacturers' promises of improved safety, vehicle pedestrian detection can be highly variable," citing an October 2023 incident in San Francisco in which a driverless vehicle struck a pedestrian (Cummings and Bauchwitz, 2024, p.8). That incident led to robotaxi company Cruise's indefinite suspension in California (Cano, 2024). News reports have further pointed out the disruption AVs have had in city systems, such as interfering with firefighting duties (Angwin, 2023). The lack of national regulatory standards in the US for AV safety testing is just one example of the policy challenge cities face towards reaping the benefits of automated mobility systems. Pande and Taeihagh (2023) present Singapore as a case study into the necessity of government involvement for coordinating robust regulation and addressing complex issues such as ethical dilemmas and social connectedness in governing autonomous systems. There is a diversity of approaches to the negotiation of urban road space between AVs and pedestrians, from those centring analyses of technical developments to those speculating the outcomes of possible policy responses.

### 3 Nexus B: People, devices and data

Kellerman (2023) refers to the "virtual mobility" of today's technology presenting users with new opportunities for human interaction as well as the extensibility of the self. Mobile users are equipped to exploit real-time information through a combination of devices, services and algorithms while moving through urban areas (Miller et al., 2021). Current initiatives into understanding

hybrid-urban space range in focus, methods and intended outcomes. HybGen: Young generations trapped in hybrid lifestyles is a research project based in Oslo and Lisbon focusing on survival strategies employed by young adults in the domains of housing and work amid urban digital transitions (Dinâmia'cet-Iscte, 2024). Another example is the Massachusetts Institute of Technology's Smart Curbs (Senseable City Lab, 2023), which uses sensors attached to public buses to analyse realtime data on how urban sidewalks are being used. Hybrid technologies are actively reshaping public spaces, as seen with Pastguide, a collaboration with the Historical Museum of Krakow and Rarelight Immersive that used mobile devices to extend the cultural institution into public space while collaborating with local vendors (Filipowiak, 2020).

Plenty of research exists on pedestrians' sensory distraction via mobile use in public spaces. Methods include observational studies, surveys, agent modelling and experimental procedures involving technologies such as eye-tracking systems. Mobile use was found to be widespread by pedestrians, affecting street crossing behaviour (Frej et al., 2022) and increasing inattentiveness on streets (Gruden et al., 2021). In other high-traffic areas, such as transit stations, mobile use by pedestrians is more likely to disrupt the efficiency of traffic flows (Shen et al., 2022). These types of inquiries tend to focus on the impact of technology use on pedestrians' movement and physical engagement with the environment around them. Other inquiries look at the effect of digital technology use on mental, social, or other forms of engagement with urban areas.

Lu (2023)'s study asked participants to take leisure walks through an urban centre while engaged with their mobile phones, commenting on how the devices "[reconfigure] the space-time relationships between a pedestrian and their surroundings". Pedestrians' interpretations of their surroundings were found to be supplemented by mobile use in a complex interplay between "various sensory inputs, memories/lived experiences, spatial knowledge, urban design, habits, personal interests and preferences" (Lu, 2023, p.90). Kalin and Frith (2016, p.223) argue that smartphones and wearable tech "have become the invisible infrastructure for

the production of embodied space" in urban settings. Through devices which navigate, capture and represent space, pedestrians combine both data and rhetorical memory in new forms of urban interaction. By the network logic which enables urban digital infrastructures, hybridity in public spaces enables new forms of interconnection and sociability between users (Xu et al., 2023).

The integration of the internet of things devices (the network of physical devices, vehicles or appliances that share data) into the built environment creates urban data infrastructures which affect physical everyday systems in cities (Barns, 2020, Dodds et al., 2021). Location-based services and technologies integrate data and virtual objects into the embodied cityscape which is otherwise experienced physically through human senses. Widespread use of smartphone applications results in the production of spatial and demographic data, possibly unknown to both data subjects and city authorities (de Souza e Silva, 2017). Pedestrians are subject to invasive sensors by commercial third parties in the "digital public space", the majority of which are unaccounted for and constitute a serious privacy threat (Marsic, 2022). Possible policy solutions to public data exploitation include the city of Amsterdam's approach which requires commercial actors to register any sensors installed in public spaces or the city of Leeds's questionnaire to suppliers of technology. In a report published by the Open Data Institute for Arup, researchers explore options for data-sharing infrastructures, including data-sharing agreements, data pooling, and decentralised open data (Dodds et al., 2021). Data infrastructure, like physical infrastructure, must be assessed on the grounds of resilience, longevity, and access to equip cities with the necessary tools to tackle future hybrid developments.

### 4 Nexus C: Public space and street design

The future of AVs on roads and the increasing hybridisation of public space has prompted urban planners to think about the necessary design changes that are needed to improve safety, efficiency and citizen engagement. The deployment of AVs in urban areas could lead to more efficient

LSE Cities Briefing Papers

Rode and Bhargava 2024

land use, reduced parking needs, reduced emissions and improved air quality (Orieno et al., 2024). Roadway infrastructure is an immediate area for consideration; models of the effects of dedicated AV lanes in diverse roadways estimate that at a higher market penetration rate, dedicated lanes could reduce traffic accidents by 50 per cent (Sha et al., 2024) and substantially increase ridership (Zhang et al., 2023). However, though changes to roadway infrastructure may influence activity surrounding vehicle use, pedestrian behaviour is less affected (Zou et al., 2023). Cummings and Bauchwitz (2024) also show that increased markings on roadways risk lowering the performance of detection systems in AVs. Plihal et al. (2022) propose an automated urban parking system with a communication protocol that connects AVs, parking infrastructure and drivers. The field of urban design, equipped with emerging and refined hybrid technologies faces new issues in the face of ongoing technological developments in public space.

From models to real streets, changes in urban design involve several physical and digital components that must be accounted for. Effective and sustainable adoption of AVs in cities requires both digital infrastructural development and legislation to promote commercial uptake (Jovanović et al., 2023). Rather than simply matching city designs and policies with AVs' technological innovations, Sandhaus, Ju and Yang (2023) propose iterative simultaneous prototyping of AVs, city designs and policies. On pedestrian behaviour, Kalatian and Farooq (2021) suggest educational programmes, enhanced safety measures, active modes of transportation and traffic rule reform as potentially viable and urgent interventions. The interconnections among AV, city and policy design decisions can be mapped to identify the key barriers in combining them. Implications of hybrid technology on urban design extend beyond roadways and crossings and into heavy pedestrian traffic areas such as metro transit stations (Shen et al., 2022) and retail centres. The design processes of these spaces necessitate a systems approach to attend to all involved actors accurately and holistically.

#### 5 Conclusion

Hybrid public space demonstrably involves several co-dependent systems including but not limited to AVs, public digital infrastructure, street design, hybrid pedestrian culture and policy responses. Digital technology, human behaviour and the regulatory approaches of cities are co-evolving continuously. It is necessary to apply a systems perspective to prepare cities for future shocks in this complex ecosystem. The urban hybridity framework presents a modularised and layered approach with accessible entry points to an otherwise overwhelming set of issues.

### References

- ANGWIN, J. (2023). Autonomous vehicles are driving blind. *New York Times*, 11 October 2023.
- BARNS, S. (2020). Platform Urbanism: negotiating platform ecosystems in connected cities, Singapore, SINGAPORE, Springer Singapore Pte. Limited.
- BELLET, T., LAURENT, S., BORNARD, J.-C., HOANG, I. AND RICHARD, B. (2022). Interaction between pedestrians and automated vehicles: Perceived safety of yielding behaviors and benefits of an external human–machine interface for elderly people. *Frontiers in Psychology*, p.13.
- CAMPS-ARAGÓ, P., TEMMERMAN, L.,
  VANOBBERGHEN, W. AND DELAERE,
  S. (2022). Encouraging the sustainable
  adoption of autonomous vehicles for
  public transport in Belgium: citizen
  acceptance, business models, and policy
  aspects. Sustainability, 14.
- CANO, R. (2024). One crash set off a new era for self-driving cars in S.F. Here's a complete look at what happened. *San Fransisco Chronicle*, 8 February 2024.
- CUMMINGS, M. L. AND BAUCHWITZ, B. (2024). Unreliable pedestrian detection and driver alerting in intelligent vehicles. *IEEE Transactions on Intelligent Vehicles*, pp.1–9.
- DE SOUZA E SILVA, A. (2006). From cyber to hybrid: hobile technologies as interfaces of

LSE Cities Briefing Papers Rode and Bhargava 2024

- hybrid spaces. *Space and Culture*, 9, pp.261–278.
- DE SOUZA E SILVA, A. (2017). Pokémon Go as an HRG: mobility, sociability, and surveillance in hybrid spaces. *Mobile Media & Communication*, 5, pp.20–23.
- DINÂMIA'CET-ISCTE. (2024). Young generations trapped in hybrid lifestyles: challenges in ways of living and working towards the urban green care in Lisbon and Oslo [online]. Dinamia'cet Iscte. Available from: www.dinamiacet.iscte-iul.pt/research-projects/Collective/young-generations-trapped-in-hybrid-lifestyles%3A-challenges-in-ways-of-living-and-working-towards-the-urban-green-care-in-lisbon-and-oslo? [accessed 4 March 2024].
- DODDS, L., SNAITH, B. AND MASSEY, J. (2021). Exploring new approaches for sharing data in the built environment. Open Data Institute; Arup.
- FILIPOWIAK, J. (2020). Pastguide umobile time machine case study for Historic Museum in Krakow [online] Rarelight Immersive.

  Available from:
  <a href="https://www.rarelightimmersive.com/blog/mobile-time-machine-app/">https://www.rarelightimmersive.com/blog/mobile-time-machine-app/</a> [accessed 19 February 2024].
- FREJ, D., JAŚKIEWICZ, M., POLIAK, M. AND ZWIERZEWICZ, Z. (2022). Smartphone use in traffic: a pilot study on pedestrian behavior. *Applied Sciences*, p.12.
- GOUNI, V., KEHAGIA, F. AND NALMPANTIS, D. (2022). The future of public transport in the era of sharing economy: the view of transport operators. *IOP Conference Series:* Earth and Environmental Science, 1123, 012052.
- GRUDEN, C., IŠTOKA OTKOVIĆ, I. AND ŠRAML, M. (2021). Safety analysis of young pedestrian behavior at signalized intersections: an eye-tracking study. *Sustainability*, p.13.
- GUERREIRO AUGUSTO, M., ACAR, B., SOTO, A. C., SIVRIKAYA, F. AND ALBAYRAK, S. (2024). Driving into the future: a crosscutting analysis of distributed artificial intelligence, CCAM and the platform economy. *Autonomous Intelligent Systems*, 4, p.1.

- JOVANOVIĆ, M., MATEO SANGUINO, T. D. J., DAMJANOVIĆ, M., ĐUKANOVIĆ, M. AND THOMOPOULOS, N. (2023). Driving sustainability: carbon footprint, 3D printing, and legislation concerning electric and autonomous vehicles. *Sensors*, p.23.
- KALATIAN, A. AND FAROOQ, B. (2021).

  Decoding pedestrian and automated vehicle interactions using immersive virtual reality and interpretable deep learning. *Transportation Research Part C:* emerging technologies, 124, 102962.
- KALIN, J. AND FRITH, J. (2016). Wearing the city: memory p(a)laces, smartphones, and the rhetorical invention of embodied space. *Rhetoric Society Quarterly*, 46, pp.222–235.
- KELLERMAN, A. (2023). *Understanding Personal Mobilities*. Cheltenham, UK: Edward Elgar Publishing.
- LU, W. (2023). Streets as experienced through the body, mind, and screen: the smartphone and the pedestrian's engagement with an urban public space. *Mobile Media & Communication*, 12, pp.71–94.
- MARSIC, T. (2022). When Billboards Stare
  Back: how cities can reclaim the digital
  public space [online] Nesta and the Cities
  Coalition for Digital Rights. Available
  from: <a href="www.nesta.org.uk/report/when-billboards-stare-back-how-cities-can-reclaim-the-digital-public-space/">www.nesta.org.uk/report/when-billboards-stare-back-how-cities-can-reclaim-the-digital-public-space/</a> [17 May 2022].
- MILLER, D., ABED RABHO, L., AWONDO, P., DE VRIES, M., DUQUE, M., GARVEY, P., HAAPIO-KIRK, L., HAWKINS, C., OTAEGUI, A., WALTON, S. AND WANG, X. (2021). *The Global Smartphone: beyond a youth technology.* Ageing with Smartphones. London: UCL Press.
- ORIENO, O. H., NDUBUISI, N. L., ILOJIANYA, V. I., BIU, P. W. AND ODONKOR, B. (2024). The future of autonomous vehicles in the U.S. urban landscape: a review: analyzing implications for traffic, urban planning, and the environment.

  Engineering Science & Technology Journal, 5, pp.43–64.
- PANDE, D. AND TAEIHAGH, A. (2023). Navigating the governance challenges of

- disruptive technologies: insights from regulation of autonomous systems in Singapore. *Journal of Economic Policy Reform*, 26, pp.298–319.
- PLIHAL, J., NEDOMA, P., SESTAK, V., HERDA, Z. AND AKSJONOV, A. (2022).

  Transport automation in urban mobility: a case study of an autonomous parking system. *Vehicles*, p.4.
- SANDHAUS, H., JU, W. AND YANG, Q. (2023). Towards prototyping driverless vehicle behaviors, city design, and policies simultaneously. *ArXiv*, abs/2304.06639.
- SENSEABLE CITY LAB. (2023). Smart Curbs [online]. MIT Senseable City Lab. Available from:
  <a href="https://senseable.mit.edu/smart-curbs/">https://senseable.mit.edu/smart-curbs/</a>
  [accessed 4 March 2024].
- SERVCITY (2023). ServCity: consortium celebrates completion of its project to bring autonomous mobility a step closer to deployment in the UK's cities. [online].

  Available from: <a href="https://www.servcity.co.uk">www.servcity.co.uk</a>
  [accessed date: 4 March 2024]
- SEVERINO, A., CURTO, S., BARBERI, S., ARENA, F. AND PAU, G. (2021). Autonomous vehicles: an analysis both on their distinctiveness and the potential impact on urban transport systems. *Applied Sciences*, p.11.
- SHA, H., SINGH, M. K., HAOUARI, R.,
  PAPAZIKOU, E., QUDDUS, M.,
  QUIGLEY, C., CHAUDHRY, A.,
  THOMAS, P., WEIJERMARS, W. AND
  MORRIS, A. (2024). Network-wide safety
  impacts of dedicated lanes for connected
  and autonomous vehicles. *Accident Analysis & Prevention*, 195, 107424.
- SHEN, C.-W., MAO, M.-N., HSU, Y.-T. AND MIRALINAGHI, M. (2022). Research on features of pedestrians using smartphones at transit stations based on social force model. *Transportation Research Record*, 2676, pp.708–721.

- TRAN, T. T. M., PARKER, C., WANG, Y. AND TOMITSCH, M. (2022). Designing wearable augmented reality concepts to support scalability in autonomous vehicle-pedestrian interaction. *Frontiers in Computer Science*, p.4.
- WHITE, E. (2024). China challenges the west for driverless car supremacy. *Financial Times*, 31 January 2024.
- XIA, T., LIN, X., SUN, Y. AND LIU, T. (2023). An empirical study of the factors influencing users' intention to use automotive AR-HUD. *Sustainability*, p.15.
- XU, J., PAPANGELIS, K., DUNHAM, J.,
  BOULANGER, C., LEE, J. H., LALONE,
  N. AND SAKER, M. (2023).
  Understanding social interactions in
  location-based games as hybrid spaces:
  coordination and collaboration in raiding
  in Pokémon GO. Proceedings of the 2023
  CHI Conference on Human Factors in
  Computing Systems. Hamburg, Germany:
  Association for Computing Machinery.
- ZHANG, L., QIAN, G., SONG, Z. AND WANG, D. (2023). Deploying dedicated lanes for connected and autonomous buses in urban transportation networks.

  \*Transportmetrica A: Transport Science, 19, 2005181.
- ZHANGUZHINOVA, S., MAKÓ, E., BORSOS, A., SÁNDOR, Á. P. AND KOREN, C. (2023). Communication between autonomous vehicles and pedestrians: an experimental study using virtual reality. *Sensors*, p.23.
- ZOU, F., OGLE, J., JIN, W., GERARD, P., PETTY, D. AND ROBB, A. (2023). Pedestrian Behavior Interacting with Autonomous Vehicles: role of AV operation and signal indication and roadway infrastructure [online] 2023 IEEE Conference on Virtual Reality and 3D User Interfaces Abstracts and Workshops. Available from: https://ieeexplore.ieee.org/document/1010 8822 [25–29 March 2023].

<sup>&</sup>lt;sup>i</sup> See Rode, P. and Bhargava, S. (2024). Hybrid Cities: Conceptual Framework. LSE Cities Working Paper.