

# Decisions with conflicting and imprecise information

Thibault Gajdos<sup>1</sup> and Jean-Christophe Vergnaud <sup>2</sup>

<sup>1</sup>CNRS, CERSES and Ecole Polytechnique

<sup>1</sup>CNRS, Centre d'Economie de la Sorbonne, CERSES

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# Introduction

## Decision under uncertainty

- consult experts
- decide on the basis of the collected information

## Question

How to decide on the basis of an information coming from several experts?

## Problem

- Experts might be imprecise
- Experts might disagree

# Conflict and imprecision

	Expert 1	Expert 2
Situation A	$\frac{1}{2}$	$\frac{1}{2}$
Situation B	$\frac{1}{4}$	$\frac{3}{4}$
Situation C	$[\frac{1}{4}, \frac{3}{4}]$	$[\frac{1}{4}, \frac{3}{4}]$

## *Linear aggregation rule*

$F_A = F_B = \frac{1}{2}$ : Fails to grasp conflict

## *Union rule*

- $F_B = F_C = [\frac{1}{4}, \frac{3}{4}]$
- Fails to grasp imprecision
- Smithson (1999), Cabantous (2007): "conflict aversion hypothesis"

# Aggregation and preferences

## Traditional approach

- gather information
- aggregate information
- decide

Consider directly preferences with several sources of information

# Plan

- 1 Representation theorem
- 2 Comparative imprecision and conflict aversion
- 3 Example

# Setup

- $\Omega$ : finite state space
- $P \in \mathcal{P}$ : compact convex subset of probas on  $\Omega$
- $x \in X$ : pure outcomes
- $\Delta(X)$ : simple lotteries
- $\mathcal{F} = \{f : \Omega \rightarrow \Delta(X)\}$ : acts

## Domain of preferences

$$\mathcal{F} \times \mathcal{P} \times \mathcal{P}$$

- $(f, P_1, Q_1) \succcurlyeq (g, P_2, Q_2)$
- $(f, P) \succcurlyeq^* (g, Q) \Leftrightarrow (f, P, P) \succcurlyeq (g, Q, Q)$

# Preliminaries: one source of information

## GHTV (2008)

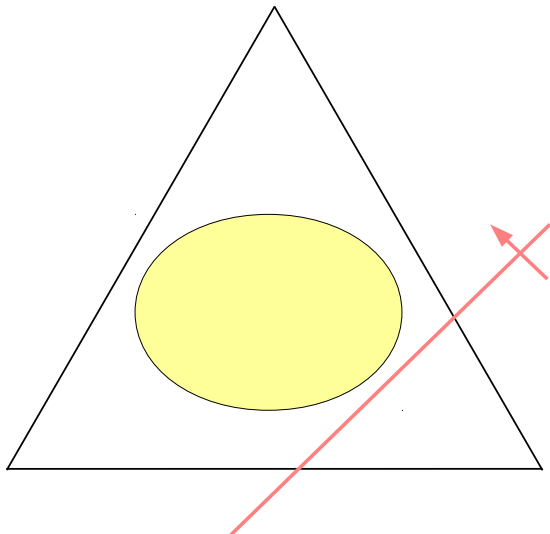
The preference  $\succsim^*$  is represented by:

$$V(f, P) = \min_{p \in \varphi(P)} \sum_{\omega} u(f(\omega)) p(\omega).$$

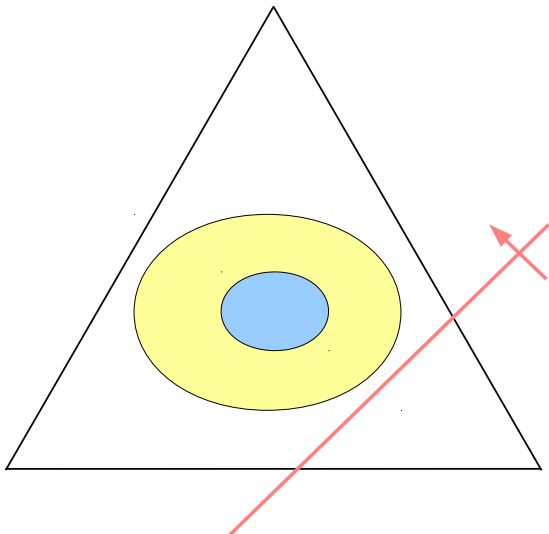
## Risk and imprecision

- $\varphi$ : attitude towards imprecision
- $u$ : attitude towards risk

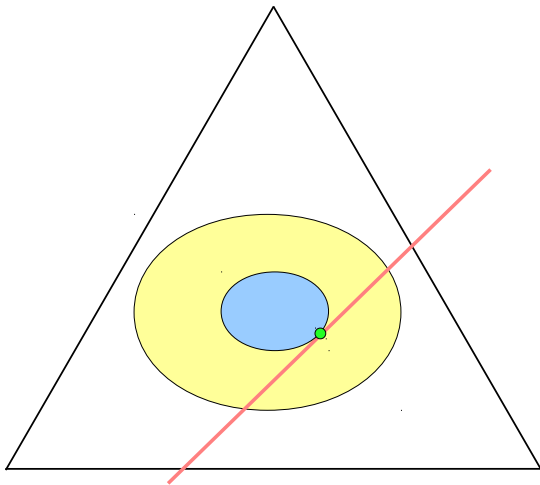
## Preliminaries: one source of information



## Preliminaries: one source of information



# Preliminaries: one source of information



# Axioms

## Extension of GHTV

$$V(f, P, Q) = \min_{p \in \psi(P, Q)} \sum_{\omega} u(f(\omega)) p(\omega).$$

## Dominance

$$\left. \begin{array}{l} (f, P_1) \succcurlyeq^* (g, P_2) \\ (f, Q_1) \succcurlyeq^* (g, Q_2) \end{array} \right\} \Rightarrow (f, P_1, Q_1) \succcurlyeq (g, P_2, Q_2)$$

# Axioms

## Consensus

- $\alpha P + (1 - \alpha)Q = \{\alpha p + (1 - \alpha)q : p \in P, q \in Q\}$
- Interpretation: the "correct" set is  $P$  with proba  $\alpha$  and  $Q$  with proba  $(1 - \alpha)$
- Both experts agree that the other expert might be right with proba  $\alpha$
- $(P, Q) \rightarrow (\alpha P + (1 - \alpha)Q, \alpha Q + (1 - \alpha)P)$
- $\alpha \rightarrow \frac{1}{2}$ : reach consensus

## Conflict Aversion

$$(f, \alpha P + (1 - \alpha)Q, \alpha Q + (1 - \alpha)P) \succcurlyeq (f, P, Q).$$

# Representation

## Theorem

There exist  $u$  linear,  $\varphi$  continuous and linear,  $\Pi \in \Delta(\{1, 2\})$  symmetric such that:

$$V(f, P, Q) = \min_{\pi \in \Pi} \pi(1) \left( \min_{p \in \varphi(P)} \sum_{\omega} u(f(\omega)) p(\omega) \right) + \pi(2) \left( \min_{p \in \varphi(Q)} \sum_{\omega} u(f(\omega)) p(\omega) \right).$$

## Equivalent representation

$$V(f, P, Q) = \min_{p \in \Pi \otimes (\varphi(P), \varphi(Q))} \sum_{\omega} u(f(\omega)) p(\omega)$$

$$\Pi \otimes (\varphi(P), \varphi(Q)) = \{\pi(1)p + \pi(2)q \mid \pi \in \Pi, p \in \varphi(P), q \in \varphi(Q)\}$$

# Comparative imprecision aversion

## Definition

Suppose there exist two prizes  $\bar{x}, \underline{x}$  in  $X$  st both  $a$  and  $b$  strictly prefer  $\bar{x}$  to  $\underline{x}$ . We say that  $\succsim_b^*$  is more averse to imprecision than  $\succsim_a^*$  whenever for all  $f \in \mathcal{F}_{\bar{x}, \underline{x}}^b$ ,  $p \in \Delta(\Omega)$ ,  $P \in \mathcal{P}$

$$(f, \{p\}) \succsim_a^* (f, P) \Rightarrow (f, \{p\}) \succsim_b^* (f, P).$$

## Proposition

The following assertions are equivalent:

- ①  $\succsim_b^*$  is more averse to imprecision than  $\succsim_a^*$ ,
- ② for all  $P \in \mathcal{P}$ ,  $\varphi_a(P) \subset \varphi_b(P)$ .

# Comparative conflict aversion

## Definition

$\succsim_b$  is more averse to conflict than  $\succsim_a$  if for all  $f \in \mathcal{F}$ ,  $P, Q \in \mathcal{P}$ ,  $\alpha \in (0, 1)$ , st both  $a$  and  $b$  prefers  $(f, P)$  to  $(f, Q)$  if :

$$(f, \alpha P + (1 - \alpha)Q, \alpha P + (1 - \alpha)Q) \succsim_a (f, P, Q)$$

then,

$$(f, \alpha P + (1 - \alpha)Q, \alpha P + (1 - \alpha)Q) \succsim_b (f, P, Q).$$

## Proposition

The following assertions are equivalent:

- 1  $\succsim_b$  is more averse to conflict than  $\succsim_a$ ,
- 2  $\Pi_a \subseteq \Pi_b$ .

## Two states

### Parametric form of $\varphi$ and $\Pi$

If  $\varphi$  is symmetric:

$$\varphi(P) = \{(1 - \theta)c(P) + \theta p \mid p \in P\},$$

$$\Pi = \left\{ (1 - \alpha) \left( \frac{1}{2}, \frac{1}{2} \right) + \alpha(t, 1 - t) \mid t \in [0, 1] \right\},$$

## Two states

### Proposition

Assume  $|\Omega| = 2$  and  $\varphi(P)$  is symmetric. Then the following are equivalent:

- (i) For all  $P, Q \in \mathcal{P}$ , there exists  $R \in \mathcal{P}$  such that  $\Pi \otimes (\varphi(P), \varphi(Q)) = \varphi(R)$ ;
- (ii)  $\theta \geq \alpha$ .

"conflict aversion hypothesis"  $\Leftrightarrow \alpha > \theta$

## Two states

### Proposition

Assume  $|\Omega| = 2$  and  $\varphi(P)$  is symmetric. Then the following statements are equivalent:

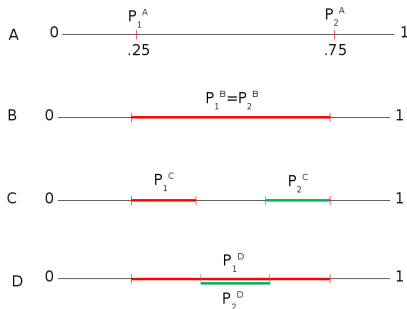
- (i) For all  $P, Q \in \mathcal{P}$ ,  $\Pi \otimes (\varphi(P), \varphi(Q)) = \varphi(\Pi \otimes (P, Q))$ ;
- (ii)  $\theta = 1$ .

### Proposition

Assume  $|\Omega| = 2$  and  $\varphi(P)$  is symmetric. Then the following statements are equivalent:

- (i) For all  $P, Q \in \mathcal{P}$ ,  $\Pi \otimes (\varphi(P), \varphi(Q)) = \varphi(\text{co}(P \cup Q))$ ;
- (ii)  $(\alpha, \theta) = (1, 1)$ .

# Illustration



$1 \geq \theta \geq \frac{3\alpha}{\alpha+2}$	$\frac{3\alpha}{\alpha+2} \geq \theta \geq \frac{4\alpha}{3+\alpha}$	$\frac{4\alpha}{3+\alpha} \geq \theta \geq \alpha$	$\alpha \geq \theta \geq 0$
A	A	D	D
C	D	A	B
D	C	C	C
B	B	B	A